

A comparison of Parallel and Sequential Niching Methods

Introduction

Niching Methods promote the formation and maintenance of stable subpopulations in GA
Examine four niching methods and compare performance on classification/multimodal function optimization

- Parallel niching methods : Sharing, crowding
- Sequential niching methods
- Parallel hill-climber

Parallel Niching-Sharing

Sharing derates each population element's fitness by amount related to the number of similar individuals in the population

$$f'(i) = \frac{f(i)}{\sum_{j=1}^n sh(d(i, j))}$$

$$sh(d) = \begin{cases} 1 - \left(\frac{d}{\sigma_{share}}\right)^\alpha, & \text{if } d < \sigma_{share} ; \\ 0, & \text{otherwise,} \end{cases}$$

Shared fitness, niche count, sharing function, threshold: if distance between two population elements is greater than threshold, they do not affect each others shared fitness

Parallel Niching-Crowding

Insert new elements into the population by replacing similar elements

Deterministic crowding(DC)

Deterministic Crowding

(REPEAT for g generations)

DO $n/2$ times:

1. Select 2 parents, p_1 and p_2 , randomly, no replacement
2. Cross them, yielding c_1 and c_2
3. Apply mutation / other operators, yielding c'_1 and c'_2
4. IF $[d(p_1, c'_1) + d(p_2, c'_2)] \leq [d(p_1, c'_2) + d(p_2, c'_1)]$
 - IF $f(c'_1) > f(p_1)$ replace p_1 with c'_1
 - IF $f(c'_2) > f(p_2)$ replace p_2 with c'_2

ELSE

- IF $f(c'_2) > f(p_1)$ replace p_1 with c'_2
- IF $f(c'_1) > f(p_2)$ replace p_2 with c'_1

Parallel hillclimbing

Starts with random generated initial population, forces each element to converge to its nearest attractor

Similar with binary search

Parallel Hillclimbing (Phenotypic)

1. Initialize *Step Size*
2. WHILE *Step Size* $\geq \epsilon$
 - (a) FOR each population element
 - Randomly pick a starting variable
 - *Change* = TRUE
 - WHILE *Change*
 - *Change* = FALSE
 - FOR each variable
 - * IF adding *Step Size* to current variable yields improved fitness
 - Perform the addition
 - *Change* = TRUE
 - * ELSE IF subtracting *Step Size* from current variable yields improved fitness
 - Perform the subtraction
 - *Change* = TRUE
 - (b) *Step Size* = *Step Size* / 2

Sequential niching(SN)

Simple GA, Maintaining the best solution of each run offline

Call multiple runs that sequential niching performs to solve a single problem-sequence

Niche radius : to avoid converging to the same area of the search space multiple times

- depress the fitness landscape at all points in radius of solution
- similar with threshold in sharing method

Parallel vs Sequential

Advantage of SN

- simplicity
- ability to work with smaller population
- speed

Disadvantage of SN

- Loss through deration of optimal solution/building blocks
- Repeated search of depressed regions
- Repeated convergence to the same solution

Test problems

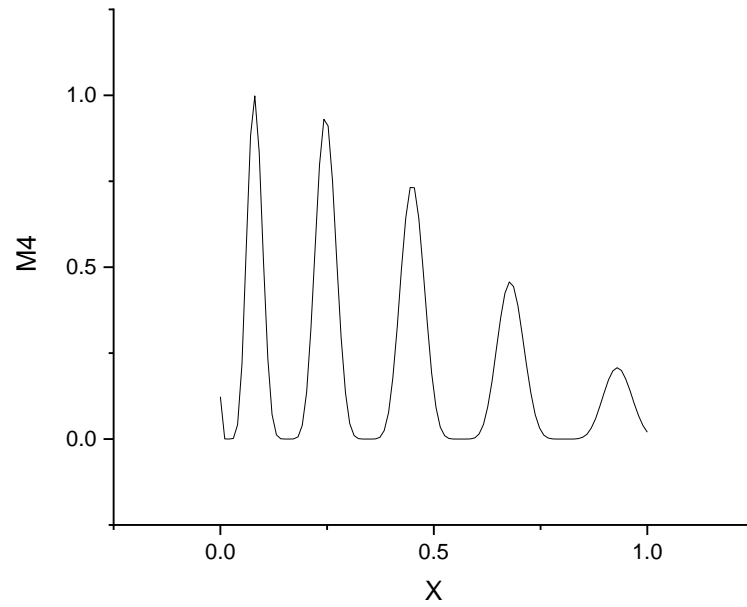
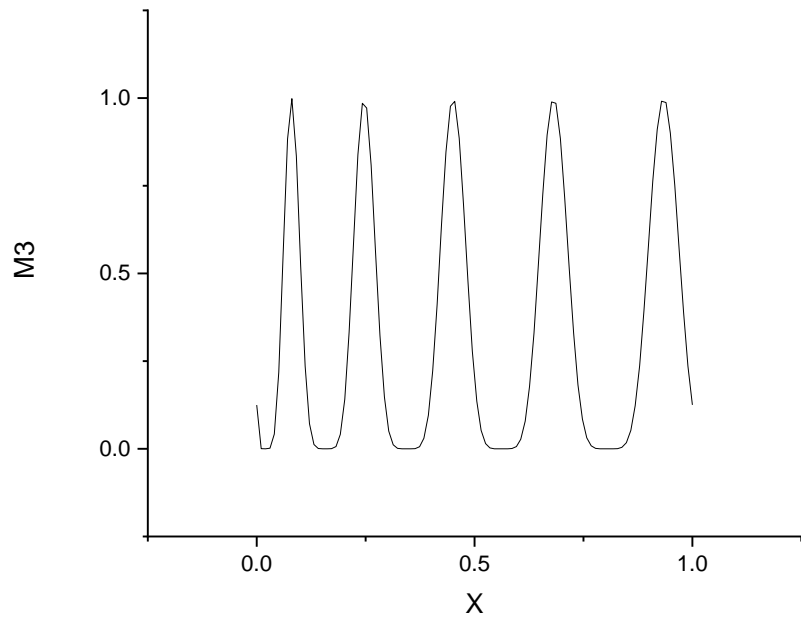
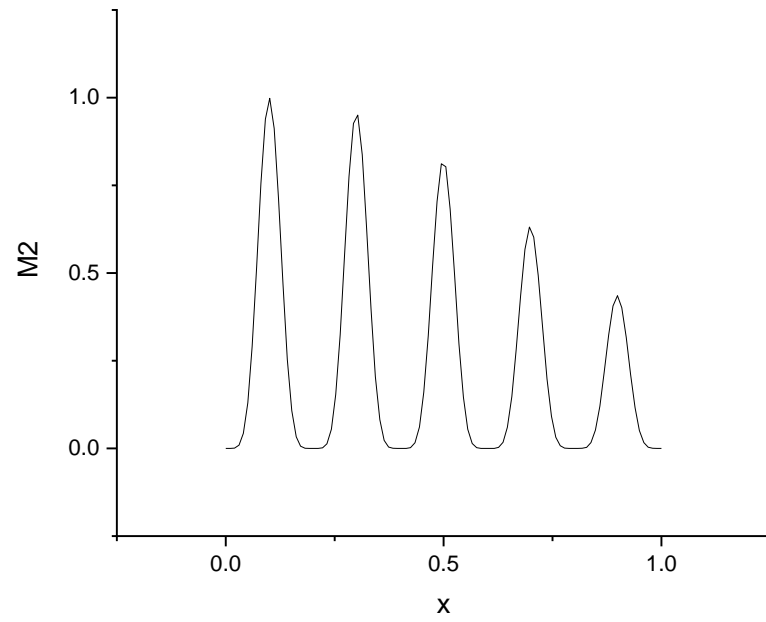
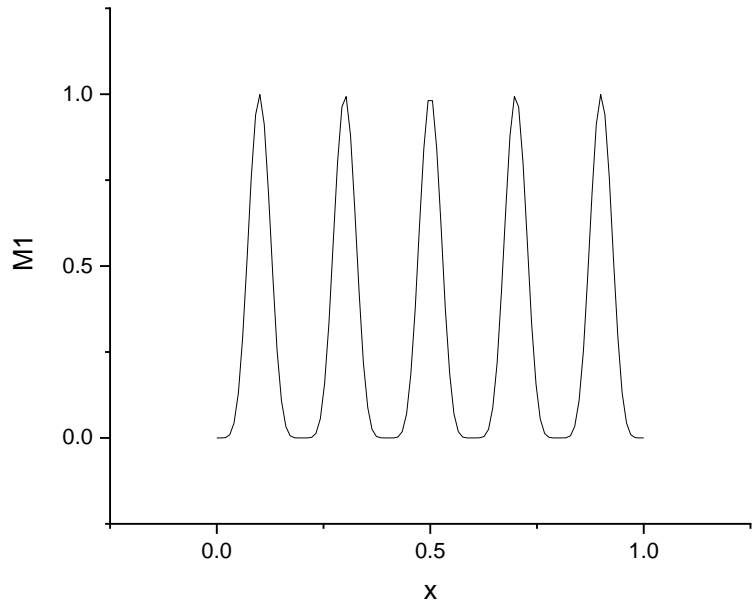
M1-M9 : optimization problems

MUX-6, PAR-8 : classification problems

M1~M4: one dimensional, five-peaked
sinusoidal functions

Equally-spaced peaks/not equally spaced peaks

Peaks with uniform height/not uniform height



Test problems: M5,M6

M5: two dimensional functions with four peaks of identical height

M6: two dimensional functions with 25 peaks of differing heights

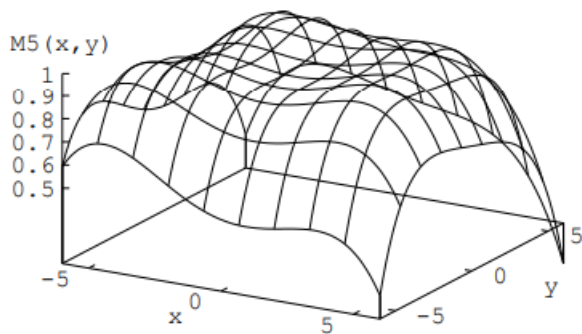


Figure 2: Test Function $M5$ is displayed.

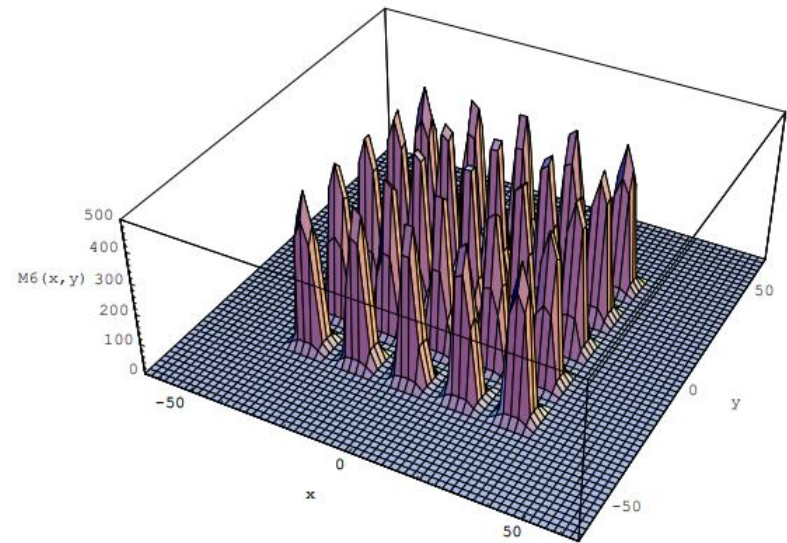


Figure 3: Test Function $M6$ is displayed.

Test problems: M7, M8, M9

Massively multimodal, deceptive function

Hardest test problems

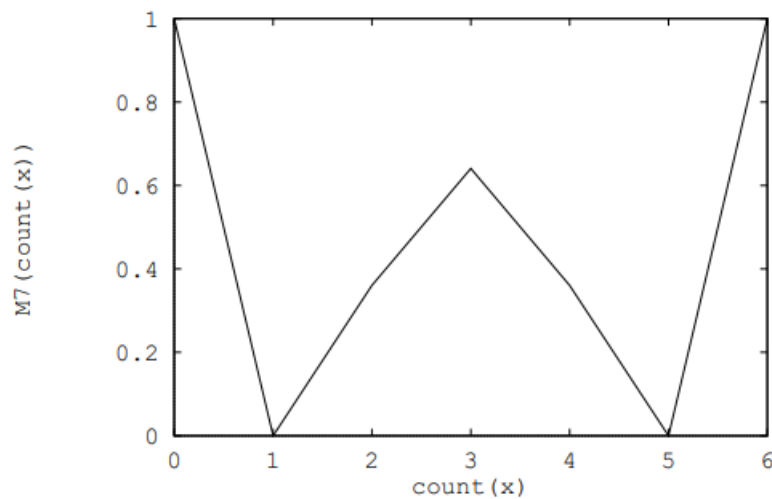


Figure 4: Test Function $M7$ is displayed.

Test problems: MUX-6, PAR-8

Classification problem

$$f(POS, NEG) = \begin{cases} 1 + POS & \text{if } NEG = 0 ; \\ 1 - \frac{NEG}{NTX} & \text{otherwise .} \end{cases}$$

MUX-6 : six bit multiplexer problem

PAR-8: 8 bit parity problem

Easiest problem : MUX-6

Intermediate difficulty PAR-8

Result

Easiest problem : M1~M5, MUX-6

Intermediate difficulty : M6, PAR-8

Hardest problem : M7~M9,

Compare the number of GA function(except HC)

Compare total number of function evaluations

Result-Case 1

Most of the case-HC has
best performance

(m1,2,5,mux-6)

For some case, DC has
best performance

(m3,4)

On easy problem, HC
works well

<i>Method</i>	\bar{n}	\bar{g}	<i>GA: μ</i>	<i>Combo: μ</i>
<i>M1</i>				
HC	2.72			1017
SN	3.68	46.40	738	4112
SH	5.76	8.00	264	2431
DC	2.40	28.00	380	1246
<i>M2</i>				
HC	2.72			1021
SN	4.64	75.60	1770	8632
SH	8.96	8.70	442	3827
DC	2.40	27.40	372	1264
<i>M3</i>				
HC	3.04			1150
SN	5.92	26.80	719	4375
SH	6.08	8.70	294	2579
DC	2.08	20.30	262	1013
<i>M4</i>				
HC	3.04			1140
SN	5.12	72.40	2445	10231
SH	6.72	9.20	352	2892
DC	2.08	17.00	210	975
<i>M5</i>				
HC	2.50			901
SN	1.30	32.30	180	1456
SH	2.80	8.00	103	1111
DC	5.60	25.60	603	2459
<i>MUX-6</i>				
HC	10.40			1257
SN	6.40	140.70	4423	9439
SH	13.60	8.90	534	1931
DC	12.00	44.30	2816	3654

Result-Case 1

SN performs poorly in most case

-SN has squashed several peaks in the fitness landscape

-once population grows large enough to locate one peak, it already locate multiple peaks

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Result-Case 2

Sharing has best performance on both case

DC is hard to find the optimal answer on M6

-DC uses non global optima as stepping-stone, dominated by other local optima

Table 2: Performances are given on the two functions of intermediate difficulty.

<i>Method</i>	\bar{n}	\bar{g}	<i>GA: μ</i>	<i>Combo: μ</i>
<i>M6</i>				
HC	12.29			29,017
SN	3.58	146.30	12,202	46,657
SH	5.12	11.80	1,638	12,910
DC			$> 1.5 \times 10^6$	
<i>PAR-8</i>				
HC	48.08			202,387
SN	19.20	36.40	100,557	263,666
SH	9.60	12.60	17,203	54,402
DC	11.20	87.40	125,850	149,022

Result-Case 3

DC only found answer on most case

M8(scaling of M7),

sharing has best

performance

-sharing is unable to solve

unscaled, massively

multimodal, deceptive

problem

Table 3: Performances are given on the three functions of greatest difficulty. Function evaluations are in thousands (indicated by the letter *K*).

<i>Method</i>	\bar{n}	\bar{g}	<i>GA: μ</i>	<i>Combo: μ</i>
<i>M7</i>				
HC				> 2000K
SN			> 1500K	
SH			> 1500K	
DC	20.80	119.80	81K	101K
<i>M8</i>				
HC				> 2000K
SN			> 1500K	
SH	19.20	19.20	13K	38K
DC	22.40	134.40	98K	119K
<i>M9</i>				
HC				> 2000K
SN			> 1500K	
SH				> 2000K
DC	136.53	337.80	1253K	1342K

Discussion

-HC is best for easiest problems, but hard to solve high difficulty problems

-SN is weak on easy problems, and unable to solve harder problems. In most cases HC works better because it does not destroy fitness landscape

-Sharing works on all levels of complexity, but doesn't work when it has extraneous peaks that are similar in fitness to the desired peaks (use scaling)

-DC is generally good for all levels, but it can lose lower optima